

# INSTITUTO SUPERIOR TÉCNICO

DSP 10/11 — Digital Signal Processing, 2<sup>nd</sup> Exam, June 25<sup>th</sup>, 2011

Duration: 3 hours. Justify all your answers (results that are not explained or justified may count less, even if they are correct).

[4 val.]

1. Consider the causal LTI system for which the input  $x[n]$  and the output  $y[n]$  satisfy the difference equation

$$y[n] - 3y[n-1] = x[n] - x[n-1].$$

- a) Find its system function,  $H(z)$ , and corresponding region of convergence.
- b) Find its impulse response,  $h[n]$ .
- c) Is the system stable?
- d) Find the output  $y[n]$  when the input is  $x[n] = 3(-3)^n u[n]$ .

[3 val.]

2. Consider two finite-length signals,  $x[n]$  and  $y[n]$ , that are zero outside the range  $0 \leq n \leq 9$ . We know the values of  $x[n]$  and the Fourier Transform (FT) of  $y[n]$ :

$$x[n] = \begin{cases} 1 & \text{if } 0 \leq n \leq 9; \\ 0 & \text{otherwise.} \end{cases}, \quad Y(e^{j\omega}) = 2e^{-j\omega} + e^{-3j\omega}.$$

- a) Find  $X[k]$ , the 20-point DFT of  $x[n]$ .
- b) Find  $Y[k]$ , the 20-point DFT of  $y[n]$ .
- c) Find and sketch the signal with DFT given by  $X[k]Y[k]$  (20-point DFTs).

[3 val.]

3. We want to find the impulse response  $h[n]$  of a FIR system that approximates an ideal low-pass filter with cut-off frequency  $\pi/4$ , using the windowing method.

- a) What is the impact of the choices of the type and dimension of the window?
- b) Find the FIR filter, using a 3-point rectangular window, *i.e.*, find  $h[0]$ ,  $h[1]$ , and  $h[2]$ .
- c) Find the amplitude of the output of the FIR filter when the input is sinusoidal with frequency  $\pi/2$  and amplitude 1. (if you did not solve b), consider  $h[0] = 3$ ,  $h[1] = -2$ , and  $h[2] = 3$ .)

[6 val.]

4. Consider noisy observations of the sum of two sinusoidal signals,

$$x[n] = A \cos(\omega_a n) + B \cos(\omega_b n) + w[n], \quad 0 \leq n \leq N-1,$$

where the parameters  $A$  and  $B$  are unknown and  $w$  is zero mean white Gaussian noise (WGN) with variance  $\sigma^2$ . The frequencies of the signals are known:  $\omega_a = 6\pi/N$  e  $\omega_b = 10\pi/N$  (note that, in this case, we obtain  $\sum_{n=0}^{N-1} \cos(\omega_a n) \cos(\omega_b n) = 0$  and  $\sum_{n=0}^{N-1} \cos^2(\omega_a n) = \sum_{n=0}^{N-1} \cos^2(\omega_b n) = N/2$ ).

- a) Find the Cramer-Rao bound (CRB) for the estimation of  $A$  and  $B$ .
- b) Find expressions for the maximum likelihood (ML) estimates of  $A$  e  $B$ .
- c) Are those estimates unbiased?
- d) Are those estimates efficient?
- e) If we knew the true value of  $B$ , could we estimate  $A$  with higher accuracy?
- f) Repeat e), now for the case where the frequencies do not have the expressions above (to completely clarify your answer, use a particular case that results simple, e.g.,  $N = 2$ ,  $\omega_a = \pi/2$ , and  $\omega_b = \pi/3$ ).

[4 val.]

5. Consider the observation model  $x = A + w$ , where the noise  $w$  follows a Gaussian distribution with zero mean and unit variance and  $A$  is a random variable, independent from  $w$ , from which we know the *a priori* distribution.

- a) Consider that  $A$  is *a priori* Gaussian with mean 4 and variance 2. We observed  $x = 7$ . Find the minimum mean square error (MMSE) estimate of  $A$ .
- b) Now consider the that *a priori*  $A$  has mean 4 but it is uniformly distributed between 0 e 8. Sketch the *a posteriori* probability density function of  $A$ ,  $p(A|x)$ , as a function of  $A$ , for fixed  $x$  (do not compute the normalization factors but present sketches for the values of  $x$  that originate qualitatively different plots), and find the maximum *a posteriori* (MAP) estimate of  $A$  as a function of  $x$ .